## Shared-Variable Concurrency

## Parallel Composition (or Concurrency Composition)

Syntax:

$$
(\mathrm{Comm}) c::=\ldots|c| \mid c
$$

Note we allow nested parallel composition, e.g., $\left(c_{0} ;\left(c_{1} \| c_{2}\right)\right)$.

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Operational Semantics:

$$
\begin{array}{lc}
\frac{\left(c_{0}, \sigma\right) \longrightarrow\left(c_{0}^{\prime}, \sigma^{\prime}\right)}{\left(c_{0} \| c_{1}, \sigma\right) \longrightarrow\left(c_{0}^{\prime} \| c_{1}, \sigma^{\prime}\right)} & \frac{\left(c_{1}, \sigma\right) \longrightarrow\left(c_{1}^{\prime}, \sigma^{\prime}\right)}{\left(c_{0} \| c_{1}, \sigma\right) \longrightarrow\left(c_{0} \| c_{1}^{\prime}, \sigma^{\prime}\right)} \\
\frac{\left(c_{i}, \sigma\right) \longrightarrow\left(\text { abort, } \sigma^{\prime}\right) \quad i \in\{0,1\}}{\left(c_{0} \| c_{1}, \sigma\right) \longrightarrow\left(\text { abort, } \sigma^{\prime}\right)}
\end{array}
$$

We have to use small-step semantics (instead of big-step semantics) to model concurrency.

## Examples (1)

$$
\begin{array}{l||l}
y:=x+1 ; & y:=x+1 \\
x:=y+1 & x:=x+1
\end{array}
$$

Suppose initially $\sigma(x)=\sigma(y)=0$. What are the possible results?
(1) $y=1, x=2 ;(2) y=1, x=3 ;(3) y=3, x=3 ;(4) y=2, x=3$

## Examples (2)

Search for a non-negative result of the function $f$ :

$$
k:=-1
$$

(newvar $i:=0$ in while $i \leq n \wedge k=-1$ do if $f(i) \geq 0$ then $k:=i$ else $i:=i+2$
$\|$ newvar $i:=1$ in while $i \leq n \wedge k=-1$ do if $f(i) \geq 0$ then $k:=i$ else $i:=i+2$ )

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$\|$ newvar $i:=1$ in while $i \leq n \wedge k=-1$ do if $f(i) \geq 0$ then $k:=i$ else $i:=i+2$ )

A problematic version:

$$
k:=-1
$$

(newvar $i:=0$ in while $i \leq n \wedge k=-1$ do
if $f(i) \geq 0$ then print $(i) ; \operatorname{print}(f(i))$ else $i:=i+2$
$\|$ newvar $i:=1$ in while $i \leq n \wedge k=-1$ do if $f(i) \geq 0$ then $\operatorname{print}(i) ; \operatorname{print}(f(i))$ else $i:=i+2)$

## Conditional Critical Regions

We could use a critical region to achieve mutual exclusive access of shared variables.

Syntax:

$$
(\text { Comm }) c::=\ldots \mid \text { await } b \text { then } \hat{c}
$$

where $\hat{c}$ is a sequential command (a command with no await and parallel composition).

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(\text { Comm) } c::=\ldots \mid \text { await } b \text { then } \hat{c}
$$

where $\hat{c}$ is a sequential command (a command with no await and parallel composition).
Semantics:

$$
\begin{gathered}
\frac{\llbracket b \rrbracket_{\text {boolexp }} \sigma=\text { true } \quad(\hat{c}, \sigma) \longrightarrow^{*}\left(\text { skip }, \sigma^{\prime}\right)}{(\text { await } b \text { then } \hat{c}, \sigma) \longrightarrow\left(\text { skip, } \sigma^{\prime}\right)} \\
\llbracket b \rrbracket_{\text {boolexp }} \sigma=\text { false } \\
(\text { await } b \text { then } \hat{c}, \sigma) \longrightarrow(\text { skip ; await } b \text { then } \hat{c}, \sigma)
\end{gathered}
$$

The second rule gives us a "busy-waiting" semantics. If we eliminate that rule, the thread will be blocked when the condition does not hold.

## Achieving Mutual Exclusion

$k:=-1$;
(newvar $i:=0$ in while $i \leq n \wedge k=-1$ do
(if $f(i) \geq 0$ then (await busy $=0$ then busy :=1); print $(i) ; \operatorname{print}(f(i)) ;$ busy $:=0$
else $i:=i+2$ )
|| newvar $i:=1$ in while $i \leq n \wedge k=-1$ do
(if $f(i) \geq 0$ then (await busy $=0$ then busy :=1); $\operatorname{print}(i) ; \operatorname{print}(f(i)) ;$ busy $:=0$ else $i:=i+2)$ )

## Atomic Blocks

A syntactic sugar:

$$
\text { atomic }\{c\} \stackrel{\text { def }}{=} \text { await true then } c
$$

We may also use the short-hand notation $\langle c\rangle$.
Semantics:

$$
\frac{(c, \sigma) \longrightarrow^{*}\left(\text { skip, } \sigma^{\prime}\right)}{(\text { atomic }\{c\}, \sigma) \longrightarrow\left(\text { skip }, \sigma^{\prime}\right)}
$$

It gives the programmer control over the size of atomic actions.

## Deadlock

await busy $1=0$
then busy1 := 1;
await busy0 $=0$
then busy0 $:=1$;
busy $0:=0$;
busy $1:=0$;

## Fairness

$$
\begin{aligned}
& k:=-1 \\
& \text { (newvar } i:=0 \text { in while } k=-1 \text { do } \\
& \quad \text { if } f(i) \geq 0 \text { then } k:=i \text { else } i:=i+2 \\
& \| \text { newvar } i:=1 \text { in while } k=-1 \text { do } \\
& \quad \text { if } f(i) \geq 0 \text { then } k:=i \text { else } i:=i+2)
\end{aligned}
$$

Suppose $f(i)<0$ for all even number $i$. Then there's an infinite execution in the form of:
$\ldots \longrightarrow\left(c_{1} \| c^{\prime}, \sigma_{1}\right) \longrightarrow\left(c_{2} \| c^{\prime}, \sigma_{2}\right) \longrightarrow \ldots \longrightarrow\left(c_{n} \| c^{\prime}, \sigma_{n}\right) \longrightarrow \ldots$

An execution of concurrent processes is unfair if it does not terminate but, after some finite number of steps, there is an unterminated process that never makes a transition.

## Fairness - More Examples

A fair execution of the following program would always terminate: newvar $y:=0$ in $(x:=0 ;(($ while $y=0$ do $x:=x+1) \| y:=1))$

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A fair execution of the following program would always terminate: newvar $y:=0$ in $(x:=0 ;(($ while $y=0$ do $x:=x+1) \| y:=1))$

Stronger fairness is needed to rule out infinite execution of the following program:

```
newvar \(y\) := 0 in
    ( \(x\) :=0;
    \(((\) while \(y=0\) do \(x:=1-x) \|(\) await \(x=1\) then \(y:=1))\)
    )
```


## Trace Semantics

Can we give a denotational semantics to concurrent programs?

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Can we give a denotational semantics to concurrent programs? Here we use transition traces to model the execution of programs.

Execution of ( $c_{0}, \sigma_{0}$ ) in a concurrent setting:

$$
\left(c_{0}, \sigma_{0}\right) \longrightarrow\left(c_{1}, \sigma_{0}^{\prime}\right),\left(c_{1}, \sigma_{1}\right) \longrightarrow\left(c_{2}, \sigma_{1}^{\prime}\right), \ldots,\left(c_{n-1}, \sigma_{n-1}\right) \longrightarrow\left(\text { skip, } \sigma_{n-1}^{\prime}\right)
$$

The gap between $\sigma_{i}^{\prime}$ and $\sigma_{i+1}$ reflects the intervention of the environment (other threads).
It could be infinite if $\left(c_{0}, \sigma_{0}\right)$ does not terminate:

$$
\left(c_{0}, \sigma_{0}\right) \longrightarrow\left(c_{1}, \sigma_{1}\right),\left(c_{1}, \sigma_{1}^{\prime}\right) \longrightarrow\left(c_{2}, \sigma_{2}\right), \ldots
$$

We omit the commands to get a transition trace:
or

$$
\begin{aligned}
& \left(\sigma_{0}, \sigma_{0}^{\prime}\right),\left(\sigma_{1}, \sigma_{1}^{\prime}\right), \ldots,\left(\sigma_{n-1}, \sigma_{n-1}^{\prime}\right) \\
& \quad\left(\sigma_{0}, \sigma_{0}^{\prime}\right),\left(\sigma_{1}, \sigma_{1}^{\prime}\right), \ldots
\end{aligned}
$$

## Interference-Free Traces

A trace $\left(\sigma_{0}, \sigma_{0}^{\prime}\right),\left(\sigma_{1}, \sigma_{1}^{\prime}\right), \ldots,\left(\sigma_{n-1}, \sigma_{n-1}^{\prime}\right)$ (or $\left.\left(\sigma_{0}, \sigma_{0}^{\prime}\right),\left(\sigma_{1}, \sigma_{1}^{\prime}\right), \ldots\right)$ is said to be Interference-Free iff $\forall i . \sigma_{i}^{\prime}=\sigma_{i+1}$.

## Operations over Traces

We use $\tau$ to represent individual transition traces, and $\mathcal{T}$ for a set of traces.

$$
\begin{array}{ll}
\epsilon \quad \text { empty trace } \\
\tau_{1}++\tau_{2} & \stackrel{\text { def }}{=} \text { concatenation of } \tau_{1} \text { and } \tau_{2} \\
\tau_{1} \text { if } \tau_{1} \text { is infinite. } \\
\mathcal{T}_{1} ; \mathcal{T}_{2} \stackrel{\text { def }}{=}\left\{\tau_{1}+\tau_{2} \mid \tau_{1} \in \mathcal{T}_{1} \text { and } \tau_{2} \in \mathcal{T}_{2}\right\} \\
\mathcal{T}^{0} \quad \stackrel{\text { def }}{=}\{\epsilon\} \\
\mathcal{T}^{n+1} & \stackrel{\text { def }}{=} \mathcal{T} ; \mathcal{T}^{n} \\
\mathcal{T}^{*} & \stackrel{\text { def }}{=} \bigcup_{n=0}^{\infty} \mathcal{T}^{n} \\
\mathcal{T}^{\omega} \quad \stackrel{\text { def }}{=}\left\{\tau_{0}+\tau_{1}+\ldots \mid \tau_{i} \in \mathcal{T}\right\}
\end{array}
$$

Note the difference between $\mathcal{T}^{*}$ and $\mathcal{T}^{\omega}$.

## Trace Semantics - First Try

$$
\begin{array}{ll}
\mathcal{T} \llbracket x:=e \rrbracket & =\left\{\left(\sigma, \sigma^{\prime}\right) \mid \sigma^{\prime}=\sigma\left\{x \sim \llbracket e \rrbracket_{\text {intexp }} \sigma\right\}\right\} \\
\mathcal{T} \llbracket \mathbf{s k i p} \rrbracket & =\{(\sigma, \sigma) \mid \sigma \in \Sigma\} \\
\mathcal{T} \llbracket c_{0} ; c_{1} \rrbracket & =\mathcal{T} \llbracket c_{0} \rrbracket ; \mathcal{T} \llbracket c_{1} \rrbracket
\end{array}
$$

$\mathcal{T} \llbracket$ if $b$ then $c_{1}$ else $c_{2} \rrbracket=\left(\mathcal{B} \llbracket b \rrbracket ; \mathcal{T} \llbracket c_{1} \rrbracket\right) \cup\left(\mathcal{B} \llbracket \neg b \rrbracket ; \mathcal{T} \llbracket c_{2} \rrbracket\right)$ where $\mathcal{B} \llbracket b \rrbracket=\left\{(\sigma, \sigma) \mid \llbracket b \rrbracket_{\text {boolexp }} \sigma=\right.$ true $\}$
$\mathcal{T}$ 【while $b$ do $c \rrbracket$

$$
=\left((\mathcal{B} \llbracket b \rrbracket ; \mathcal{T} \llbracket c \rrbracket)^{*} ; \mathcal{B} \llbracket \neg b \rrbracket\right) \cup(\mathcal{B} \llbracket b \rrbracket ; \mathcal{T} \llbracket c \rrbracket)^{\omega}
$$

## Trace Semantics (cont'd)

How to give semantics to newvarx :=e in $c$ ?
Definition: local-global( $x, e, \tau, \hat{\tau}$ ) iff the following are true (suppose $\tau=\left(\sigma_{0}, \sigma_{0}^{\prime}\right),\left(\sigma_{1}, \sigma_{1}^{\prime}\right), \ldots$ and $\left.\hat{\tau}=\left(\hat{\sigma}_{0}, \hat{\sigma}_{0}^{\prime}\right),\left(\hat{\sigma}_{1}, \hat{\sigma}_{1}^{\prime}\right), \ldots\right):$

- they have the same length;
- for all $x^{\prime} \neq x, \sigma_{i} x^{\prime}=\hat{\sigma}_{i} x^{\prime}$ and $\sigma_{i}^{\prime} x^{\prime}=\hat{\sigma}_{i}^{\prime} x^{\prime}$;
- for all $i, \sigma_{i+1} x=\sigma_{i}^{\prime} x$;
- for all $i, \hat{\sigma}_{i} x=\hat{\sigma}_{i}^{\prime} x$;
- $\sigma_{0} x=\llbracket e \rrbracket_{\text {intexp }} \hat{\sigma}_{0}$.
$\mathcal{T} \llbracket$ newvarx $:=e$ in $c \rrbracket=\{\hat{\tau} \mid \tau \in \mathcal{T} \llbracket c \rrbracket$ and local-global $(x, e, \tau, \hat{\tau})\}$


## Fair Interleaving

We view a trace $\tau$ as a function mapping indices to the corresponding transitions.

Definition: fair-merge $\left(\tau_{1}, \tau_{2}, \tau\right)$ iff there exist functions
$f \in \operatorname{dom}\left(\tau_{1}\right) \rightarrow \operatorname{dom}(\tau)$ and $g \in \operatorname{dom}\left(\tau_{2}\right) \rightarrow \operatorname{dom}(\tau)$ such that the following are true:

- $f$ and $g$ are monotone injections:

$$
i<j \Longrightarrow(f i<f j) \wedge(g i<g j)
$$

- $\operatorname{ran}(f) \cap \operatorname{ran}(g)=\emptyset$ and $\operatorname{ran}(f) \cup \operatorname{ran}(g)=\operatorname{dom}(\tau)$;
- $\forall i . \tau_{1}(i)=\tau(f i) \wedge \tau_{2}(i)=\tau(g i)$

Then $\mathcal{T}_{\text {fair }} \llbracket c_{1} \| c_{2} \rrbracket=$
$\left\{\tau \mid \exists \tau_{1} \in \mathcal{T}_{\text {fair }} \llbracket c_{1} \rrbracket, \tau_{2} \in \mathcal{T}_{\text {fair }} \llbracket c_{2} \rrbracket\right.$. fair-merge $\left.\left(\tau_{1}, \tau_{2}, \tau\right)\right\}$

## Unfair Interleaving

Definition: unfair-merge $\left(\tau_{1}, \tau_{2}, \tau\right)$ if one of the following are true:

- fair-merge $\left(\tau_{1}, \tau_{2}, \tau\right)$
- $\tau_{1}$ is infinite and there exist $\tau_{2}^{\prime}$ and $\tau_{2}^{\prime \prime}$ such that $\tau_{2}=\tau_{2}^{\prime}+\tau_{2}^{\prime \prime}$ and fair-merge $\left(\tau_{1}, \tau_{2}^{\prime}, \tau\right)$
- $\tau_{2}$ is infinite, and there exist $\tau_{1}^{\prime}$ and $\tau_{1}^{\prime \prime}$ such that $\tau_{1}=\tau_{1}^{\prime}++\tau_{1}^{\prime \prime}$ and fair-merge $\left(\tau_{1}^{\prime}, \tau_{2}, \tau\right)$

$$
\begin{aligned}
& \mathcal{T}_{\text {unfair } \llbracket c_{1} \| c_{2} \rrbracket} \\
& \quad=\left\{\tau \mid \exists \tau_{1} \in \mathcal{T}_{\text {unfair }} \llbracket c_{1} \rrbracket, \tau_{2} \in \mathcal{T}_{\text {unfair }} \llbracket c_{2} \rrbracket . \text { unfair-merge }\left(\tau_{1}, \tau_{2}, \tau\right)\right\}
\end{aligned}
$$

## Trace Semantics for await

$\mathcal{T}$ 【await $b$ then $c \rrbracket=$

$$
(\mathcal{B} \llbracket \neg b \rrbracket ; \mathcal{T} \llbracket \mathbf{s k i p} \rrbracket)^{*} ;
$$

$\left\{\left(\sigma, \sigma^{\prime}\right) \mid \llbracket b \rrbracket_{\text {boolexp }} \sigma=\right.$ true and there exist $\sigma_{0}^{\prime}, \sigma_{1}, \sigma_{1}^{\prime}, \ldots, \sigma_{n}$ such that

$$
\left(\sigma, \sigma_{0}^{\prime}\right),\left(\sigma_{1}, \sigma_{1}^{\prime}\right), \ldots,\left(\sigma_{n}, \sigma^{\prime}\right) \in \mathcal{T} \llbracket c \rrbracket
$$

and it is Interference-Free.\}
$\cup(\mathcal{B} \llbracket \neg b \rrbracket ; \mathcal{T} \llbracket \mathbf{s k i p} \rrbracket)^{\omega}$

## Trace Semantics (cont’d)

The semantics is equivalent to the following:

$$
\begin{aligned}
& \mathcal{T} \llbracket \subset \mathbb{I} \stackrel{\text { def }}{=} \\
& \quad\left\{\left(\sigma_{0}, \sigma_{0}^{\prime}\right), \ldots,\left(\sigma_{n}, \sigma_{n}^{\prime}\right) \mid\right. \\
& \quad \text { there exist } c_{0}, \ldots, c_{n} \text { such that } c_{0}=c, \\
& \quad \forall i \in[0, n-1] .\left(c_{i}, \sigma_{i}\right) \longrightarrow\left(c_{i+1}, \sigma_{i}^{\prime}\right), \\
& \left.\quad \text { and }\left(c_{n}, \sigma_{n}\right) \xrightarrow{\longrightarrow}\left(\text { skip }, \sigma_{n}^{\prime}\right)\right\} \\
& \quad\left\{\left(\sigma_{0}, \sigma_{0}^{\prime}\right),\left(\sigma_{1}, \sigma_{1}^{\prime}\right), \ldots \mid\right.
\end{aligned}
$$

there exist $c_{0}, c_{1}, \ldots$ such that $c_{0}=c$, and for all $\left.i,\left(c_{i}, \sigma_{i}\right) \longrightarrow\left(c_{i+1}, \sigma_{i}^{\prime}\right)\right\}$

## Problem with This Semantics

The trace semantics we just defined is not abstract enough.
It distinguishes the following programs (which should be viewed equivalent):

$$
\begin{aligned}
& x:=x+1 \\
& x:=x+1 ; \text { skip } \\
& \text { skip } ; x:=x+1
\end{aligned}
$$

Also consider the following two programs:

$$
\begin{aligned}
& x:=x+1 ; x:=x+1 \\
& (x:=x+1 ; x:=x+1) \text { choice } x:=x+2
\end{aligned}
$$

## Stuttering and Mumbling

$$
\begin{array}{cc}
\overline{\tau<\tau} & \overline{\tau<(\sigma, \sigma), \tau} \\
\frac{\tau<\tau^{\prime} \tau^{\prime}<\tau^{\prime \prime}}{\tau<\tau^{\prime \prime}} & \overline{\left(\sigma, \sigma^{\prime}\right),\left(\sigma^{\prime}, \sigma^{\prime \prime}\right), \tau<\left(\sigma, \sigma^{\prime \prime}\right), \tau} \\
& \frac{\tau<\tau^{\prime}}{\left(\sigma, \sigma^{\prime}\right), \tau<\left(\sigma, \sigma^{\prime}\right), \tau^{\prime}} \\
\mathcal{T}^{\dagger} \stackrel{\text { def }}{=}\left\{\tau \mid \tau \in \mathcal{T} \text { or } \exists \tau^{\prime} \in \mathcal{T} \cdot \tau^{\prime}<\tau\right\} \\
\mathcal{T}^{*} \llbracket c \rrbracket \stackrel{\text { def }}{=}(\mathcal{T} \llbracket c \rrbracket)^{\dagger}
\end{array}
$$

## Stuttering and Mumbling (cont'd)

The new semantics $\mathcal{T}^{*} \llbracket c \rrbracket$ is equivalent to the following:

$$
\mathcal{T} \llbracket c \rrbracket \stackrel{\text { def }}{=}
$$

$$
\left\{\left(\sigma_{0}, \sigma_{0}^{\prime}\right), \ldots,\left(\sigma_{n}, \sigma_{n}^{\prime}\right) \mid\right.
$$

$$
\text { there exist } c_{0}, \ldots, c_{n} \text { such that } c_{0}=c
$$

$$
\forall i \in[0, n-1] .\left(c_{i}, \sigma_{i}\right) \longrightarrow^{*}\left(c_{i+1}, \sigma_{i}^{\prime}\right)
$$

$$
\text { and } \left.\left(c_{n}, \sigma_{n}\right) \longrightarrow^{*}\left(\mathbf{s k i p}, \sigma_{n}^{\prime}\right)\right\}
$$

$\cup\left\{\left(\sigma_{0}, \sigma_{0}^{\prime}\right),\left(\sigma_{1}, \sigma_{1}^{\prime}\right), \ldots \mid\right.$
there exist $c_{0}, c_{1}, \ldots$ such that $c_{0}=c$,
$\forall i .\left(c_{i}, \sigma_{i}\right) \longrightarrow{ }^{*}\left(c_{i+1}, \sigma_{i}^{\prime}\right)$,
and for infinitely many $\left.i \geq 0,\left(c_{i}, \sigma_{i}\right) \longrightarrow^{+}\left(c_{i+1}, \sigma_{i}^{\prime}\right)\right\}$

