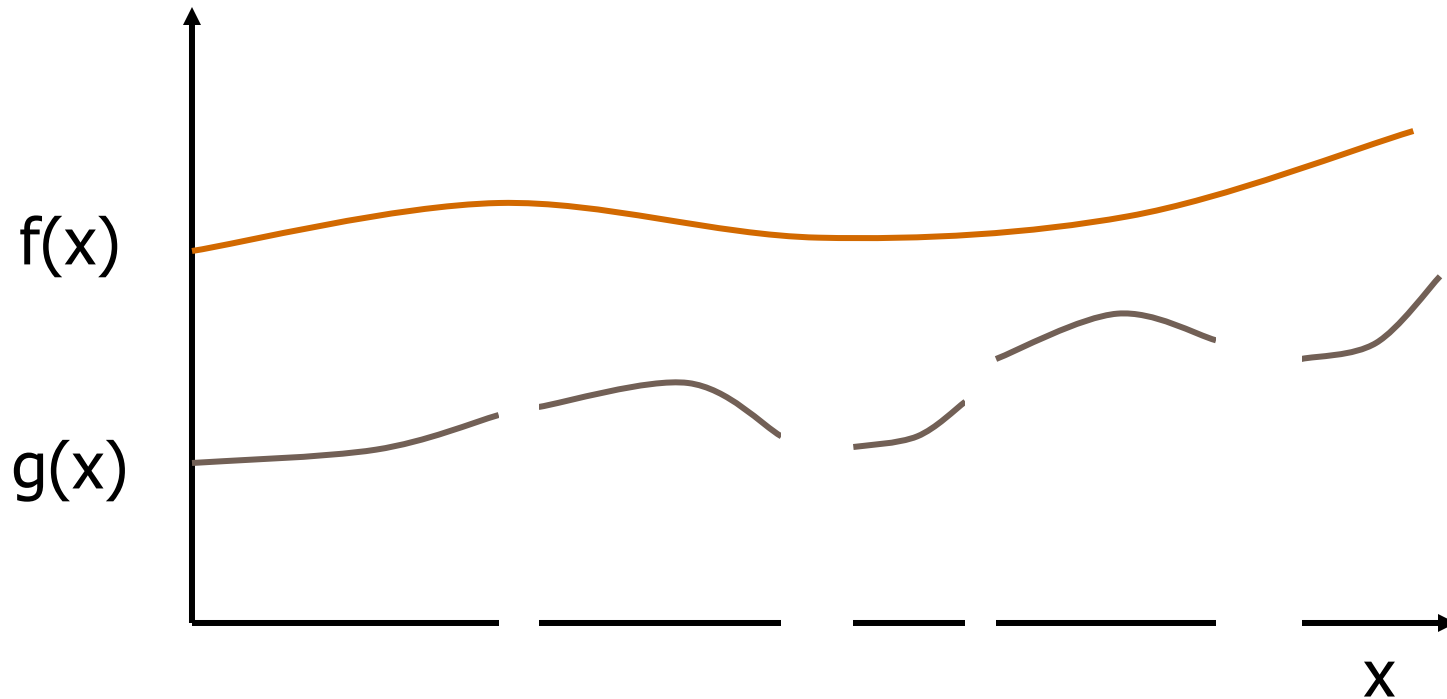


Computable Functions

Foundations: Partial, Total Functions

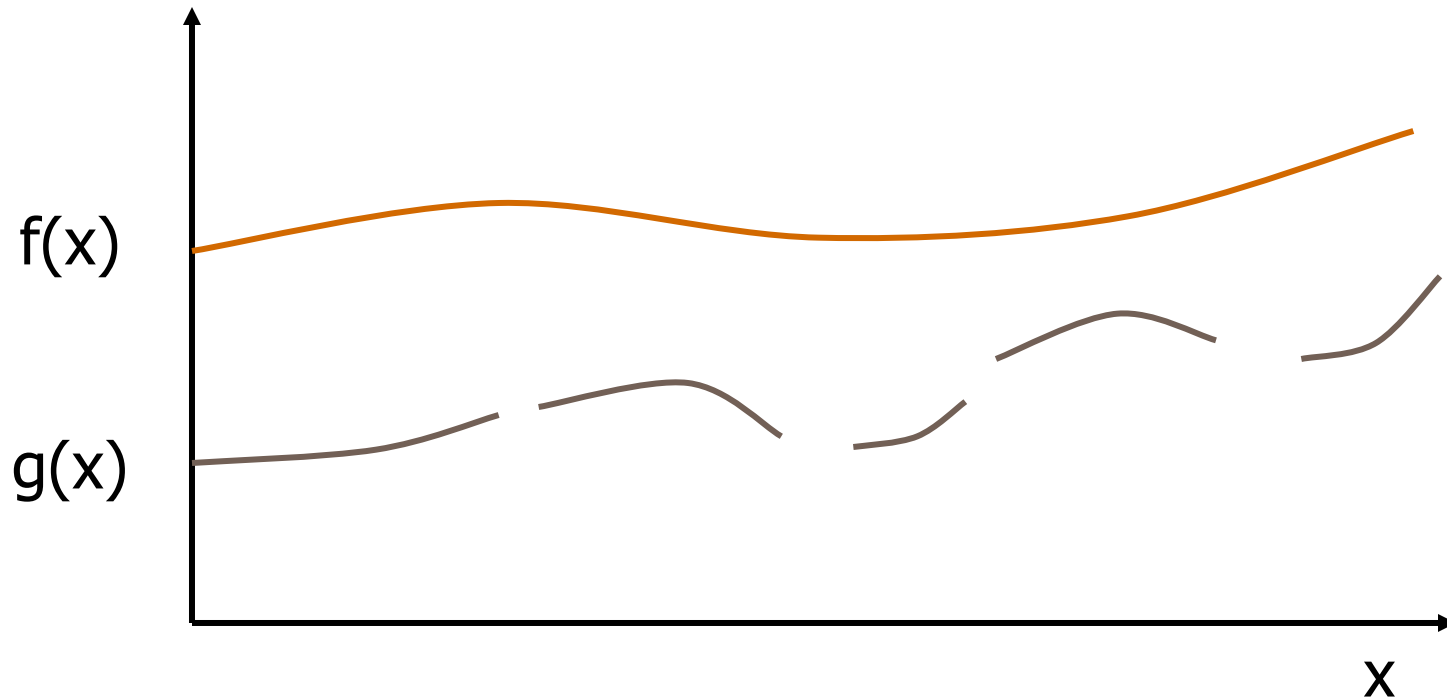
- Value of an expression may be undefined
 - Undefined operation, e.g., division by zero
 - $3/0$ has no value
 - implementation may halt with error condition
 - Nontermination
 - $f(x) = \text{if } x=0 \text{ then } 1 \text{ else } f(x-2)$
 - this is a *partial* function: not defined on all arguments
 - cannot be detected at compile-time; this is halting problem
 - These two cases are
 - “Mathematically” equivalent
 - Operationally different

Partial and Total Functions



- Total function: $f(x)$ has a value for every x
- Partial function: $g(x)$ does not have a value for every x

Functions and Graphs



- Graph of $f = \{ \langle x, y \rangle \mid y = f(x) \}$
- Graph of $g = \{ \langle x, y \rangle \mid y = g(x) \}$

Mathematics: a function is a set of ordered pairs (graph of function)

Partial and Total Functions

- Total function $f:A \rightarrow B$ is a subset $f \subseteq A \times B$ with
 - For every $x \in A$, there is some $y \in B$ with $\langle x, y \rangle \in f$ (total)
 - If $\langle x, y \rangle \in f$ and $\langle x, z \rangle \in f$ then $y = z$ (single-valued)
- Partial function $f:A \rightarrow B$ is a subset $f \subseteq A \times B$ with
 - If $\langle x, y \rangle \in f$ and $\langle x, z \rangle \in f$ then $y = z$ (single-valued)
- Programs define partial functions for two reasons
 - partial operations (like division)
 - nontermination
 - $f(x) = \text{if } x=0 \text{ then } 1 \text{ else } f(x-2)$

Computability

- **Definition**

Function f is computable if some program P computes it:
For any input x , the computation $P(x)$ halts with output $f(x)$

- **Terminology**

Partial recursive functions

= partial functions (int to int) that are computable

- **Church-Turing Hypothesis**

The programming language doesn't matter –

all “reasonable” programming languages

define the same class of computable functions

Halting function

- Decide whether program halts on input
 - Given program P and input x to P ,

$$\textit{Halt}(P,x) = \begin{cases} \text{yes} & \text{if } P(x) \text{ halts} \\ \text{no} & \text{otherwise} \end{cases}$$

Clarifications

- Assume program P requires one string input x
- Write $P(x)$ for output of P when run in input x
- Program P is string input to *Halt*
- Represent two inputs P, x as string $P\$x$ (for example)

Theorem: There is no program for *Halt*

Unsolvability of the halting problem

- Suppose P solves variant of halting problem

On input Q, assume

$$P(Q) = \begin{cases} \text{yes} & \text{if } Q(Q) \text{ halts} \\ \text{no} & \text{otherwise} \end{cases}$$

- Build program D

$$D(Q) = \begin{cases} \text{run forever} & \text{if } Q(Q) \text{ halts} \\ \text{halt} & \text{if } Q(Q) \text{ runs forever} \end{cases}$$

- Does this make sense? What can D(D) do?
 - If D(D) halts, then D(D) runs forever.
 - If D(D) runs forever, then D(D) halts.
 - **CONTRADICTION**: program P must not exist.

Examples

- Is there an algorithm to decide whether this program has a run-time type error?

if $f(x)$ then $y=1+\text{"Bob"}$ else $y=2+\text{"Alice"}$

- Is there an algorithm to decide whether this program reads variable z ?

if $f(x)$ then $y=z+\text{"Bob"}$ else $y=z+\text{"Alice"}$

Main points about computability

- Some functions are computable, some are not
 - Halting problem
 - Other problems that are equivalent
- Programming language implementation
 - *Can* report error if program result is undefined due to division by zero, other error condition
 - *Cannot* warn user if program will not terminate
 - *Many* useful program properties are *not* computable

Data Abstraction and Modularity

Reading: Sections 9.1, 9.2 (except 9.2.5), and 9.3.1

Topics

- **Modularity**
 - Interface, specification, and implementation
- **Modular program development**
 - Step-wise refinement ; Prototyping ; ...
- **Language support for modularity**
 - Procedural abstraction
 - Abstract data types
 - Representation independence
 - Datatype induction
 - Packages and modules
 - Generic abstractions
 - Functions and modules with type parameters

Modularity: Basic Concepts

- **Component**
 - Meaningful program unit
 - Function, data structure, module, ...
- **Interface**
 - Types and operations defined within a component that are visible outside the component
- **Specification**
 - Intended behavior of component, expressed as property observable through interface
- **Implementation**
 - Data structures and functions inside component

Example: Function Component

- Component
 - Function to compute square root
- Interface
 - float sqrt (float x)
- Specification
 - If $x > 0$, then $\text{sqrt}(x) * \text{sqrt}(x) \approx x$.

- Implementation

```
float sqrt (float x){  
    float y = x/2; float step=x/4; int i;  
    for (i=0; i<20; i++){if ((y*y)<x) y=y+step; else y=y-step; step = step/2;}  
    return y;  
}
```

Example: Data Type

- Component
 - Priority queue: data structure that returns elements in order of decreasing priority
- Interface
 - Type `pq`
 - Operations `empty : pq`
`insert : elt * pq → pq`
`deletemax : pq → elt * pq`
- Specification
 - Insert add to set of stored elements
 - Deletemax returns max elt and pq of remaining elts

Philosophy

- Build reusable program components
- Construct systems by divide-and-conquer
 - Limit interactions between components
 - Each component is assumed to satisfy spec
 - If another component satisfies the same specification, you can replace the first by the second
 - Internal improvements only improve the overall system, not break it

Example program using component

- Priority queue: structure with three operations
 - empty : pq
 - insert : elt * pq → pq
 - deletemax : pq → elt * pq
- Sorting algorithm using priority queue
 - begin
 - create empty pq s
 - insert each element from array into s
 - remove elements in decreasing order and place in array
 - end

This gives us an $O(n \log n)$ sorting algorithm (HW ?)

Component Dependencies

\$root		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	
org.apache.tools	ant:taskdefs	cvslib	1																
		compilers	2	.			2												
		rmic	3		.		2												
		condition	4			.	12					2	3	1					
		email	5				1												
		*	6	5	7	4	3	.											
ant	listener	7						.											
	helper	8							.						1				
	input	9					3			.					4				
	filters	10					3				.	12	1						
	types	11	4	19	7		3	152				17	.	2	9				
	util	12	1	3	3	1		55	1	1		4	13	.	12				
	*	13	11	25	14	20	10	309	4	12	3	6	71	13	.				
util	org.apache.tools.bzip2	14					4								.				
	org.apache.tools.mail	15				1		1							.				
	org.apache.tools.tar	16					4								.				
	org.apache.tools.zip	17					5								.				

source: Lattix.com

Modular program design

- Top-down design
 - Begin with main tasks, successively refine
- Bottom-up design
 - Implement basic concepts, then combine
- Prototyping
 - Build coarse approximation of entire system
 - Successively add functionality

Stepwise Refinement

- Wirth, 1971
 - “... program ... gradually developed in a sequence of refinement steps”
 - In each step, instructions ... are decomposed into more detailed instructions.
- Historical reading on web (CS242 Reading page)
 - N. Wirth, Program development by stepwise refinement, *Communications of the ACM*, 1971
 - D. Parnas, On the criteria to be used in decomposing systems into modules, *Comm ACM*, 1972
 - Both *ACM Classics of the Month*

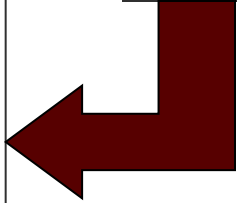
Dijkstra's Example

(1969)

```
begin
  print first 1000 primes
end
```

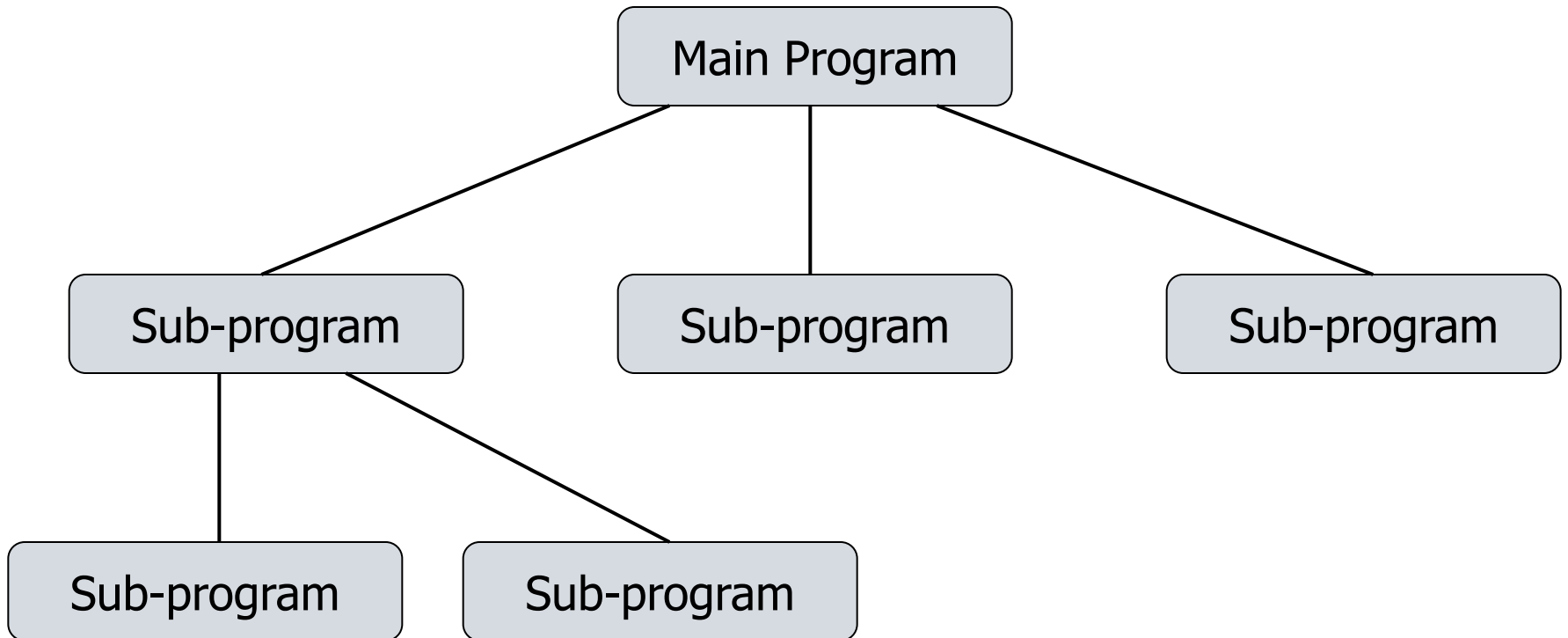


```
begin
  variable table p
  fill table p with first 1000
  primes
  print table p
end
```



```
begin
  int array p[1:1000]
  make for k from 1 to 1000
    p[k] equal to k-th prime
  print p[k] for k from 1 to 1000
end
```

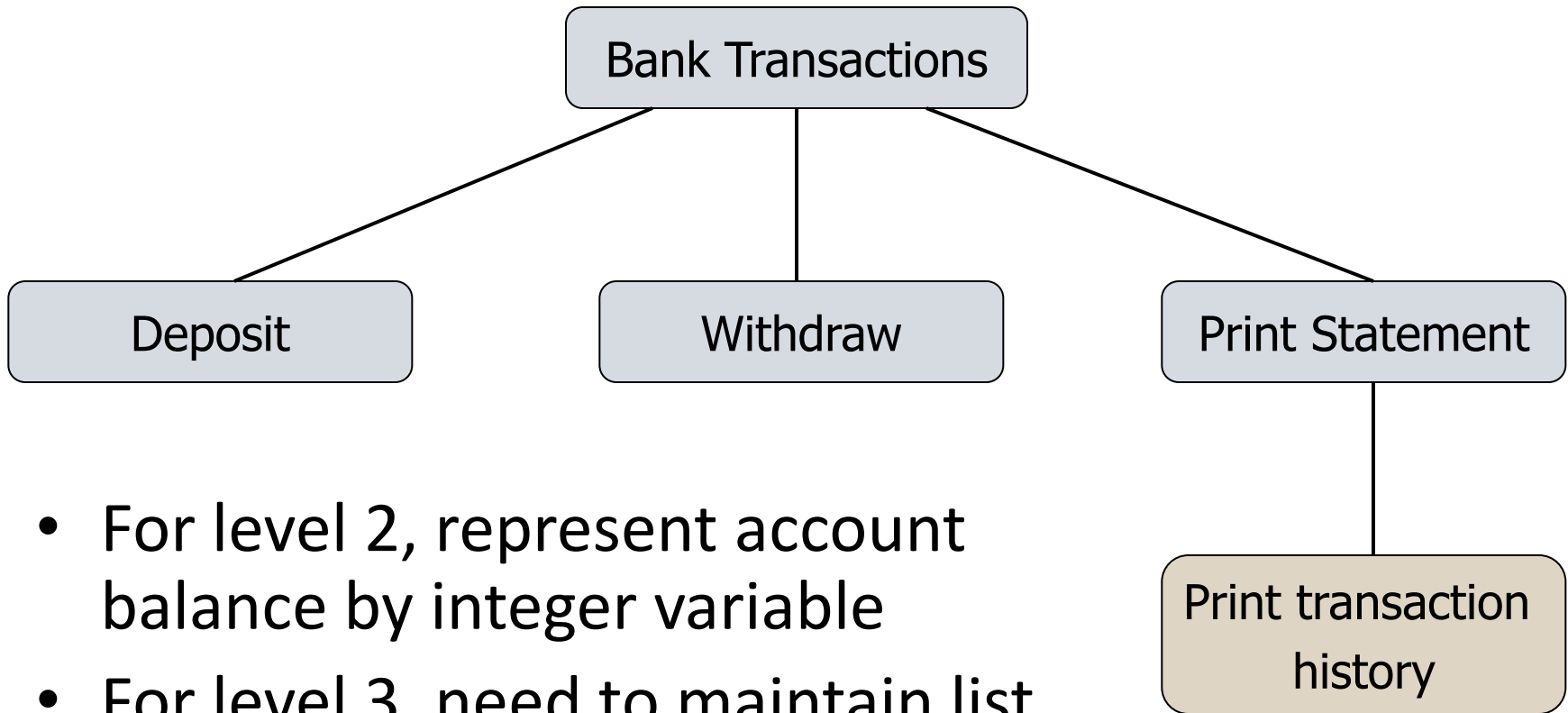
Program Structure



Data Refinement

- Wirth, 1971 again:
 - As tasks are refined, so the data may have to be refined, decomposed, or structured, and it is natural to refine program and data specifications in parallel

Example



- For level 2, represent account balance by integer variable
- For level 3, need to maintain list of past transactions

Language support for modularity

- Interface definition
 - Interface may consist of types, functions, subtype relationships, other language concepts exposed to other modules
- Isolation
 - Restrict dependence to factors visible through explicitly defined interface

Examples

- **Procedural abstraction**
 - Hide functionality in procedure or function
- **Data abstraction**
 - Hide decision about representation of data structure and implementation of operations
 - Example: priority queue can be binary search tree or partially-sorted array

Abstract Data Types

- Prominent language development of 1970's
- Main ideas:
 - Separate interface from implementation
 - Example:
 - Sets have empty, insert, union, is_member?, ...
 - Sets implemented as ... linked list ...
 - Use type checking to enforce separation
 - Client program only has access to operations in interface
 - Implementation encapsulated inside ADT construct

ML Abstype

- Declare new type with values and operations

```
abstype t = <tag> of <type>
```

```
  with
```

```
    val <pattern> = <body>
```

```
    ...
```

```
    fun f(<pattern>) = <body>
```

```
    ...
```

```
  end
```

- Representation

```
t = <tag> of <type>  similar to ML datatype decl
```

Abstype for Complex Numbers

- **Input**

```
abstype cmplx = C of real * real with
  fun cmplx(x,y: real) = C(x,y)
  fun x_coord(C(x,y)) = x
  fun y_coord(C(x,y)) = y
  fun add(C(x1,y1), C(x2,y2)) = C(x1+x2, y1+y2)
end
```

- **Types (compiler output)**

```
type cmplx
val cmplx = fn : real * real -> cmplx
val x_coord = fn : cmplx -> real
val y_coord = fn : cmplx -> real
val add = fn : cmplx * cmplx -> cmplx
```

Abstype for finite sets

- **Declaration**

```
abstype 'a set = SET of 'a list with
  val empty = SET(nil)
  fun insert(x, SET(elts)) = ...
  fun union(SET(elts1), Set(elts2)) = ...
  fun isMember(x, SET(elts)) = ...
end
```

- **Types** (compiler output)

```
type 'a set
val empty = - : 'a set
val insert = fn : 'a * ('a set) -> ('a set)
val union = fn : ('a set) * ('a set) -> ('a set)
val isMember = fn : 'a * ('a set) -> bool
```

Origin of Abstract Data Types

- **Structured programming, data refinement**
 - Write program assuming some desired operations
 - Later implement those operations
 - Example:
 - Write expression parser assuming a symbol table
 - Later implement symbol table data structure
- **Research on extensible languages**
 - What are essential properties of built-in types?
 - Try to provide equivalent user-defined types
 - Example:
 - ML sufficient to define list type that is same as built-in lists

Comparison with built-in types

- **Example: int**
 - Can declare variables of this type `x: int`
 - Specific set of built-in operations `+, -, *, ...`
 - No other operations can be applied to integer values
- **Similar properties desired for abstract types**
 - Can declare variables `x : abstract_type`
 - Define a set of operations (give interface)
 - Language guarantees that only these operations can be applied to values of `abstract_type`

Modules

- General construct for information hiding
- Two parts
 - Interface:
 - A set of names and their types
 - Implementation:
 - Declaration for every entry in the interface
 - Additional declarations that are hidden
- Examples:
 - Modula modules, Ada packages, ML structures, ...

Modules and Data Abstraction

```
module Set
  interface
    type set
    val empty : set
    fun insert : elt * set -> set
    fun union : set * set -> set
    fun isMember : elt * set -> bool
  implementation
    type set = elt list
    val empty = nil
    fun insert(x, elts) = ...
    fun union(...) = ...
    ...
end Set
```

Can define ADT

Private type

Public operations

More general

Several related types and operations

Some languages provide

Separate interface and implementation

One interface can have multiple implementations

Haskell modules

- Hide and selectively export declarations

Export list

```
module Tree ( Tree(Leaf,Branch), fringe ) where
```

Declarations {

```
  data Tree a  = Leaf a | Branch (Tree a) (Tree a)
  fringe :: Tree a -> [a]
  fringe (Leaf x)          = [x]
  fringe (Branch left right) = fringe left ++ fringe right
```

Basic description: <http://www.haskell.org/tutorial/modules.html>

More information: <http://www.haskell.org/onlinereport/modules.html>

Generic Abstractions

- Parameterize modules by types, other modules
- Create general implementations
 - Can be instantiated in many ways
- Language examples:
 - Ada generic packages, C++ templates, ML functors,
...
 - ML geometry modules in supplementary readings
 - C++ Standard Template Library (STL) provides
extensive examples

Summary

- **Modularity**
 - Interface, specification, and implementation
- **Modular program development**
 - Step-wise refinement ; Prototyping ; ...
- **Language support for modularity**
 - Procedural abstraction
 - Abstract data types
 - Representation independence
 - Datatype induction
 - Packages and modules
 - Generic abstractions
 - Functions and modules with type parameters
- **Modularity is supported by object-oriented languages, but did not originate with OOP**

